Representations of Boolean Functions in Constructive Type Theory

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• Goal:

Define a *informative canonical* representation of boolean functions in Coq \implies prime trees.

• Why:

Coq's type theory is intentional.

• How:

By showing that boolean functions and prime trees are isomorphic.

Prime Trees \cong Boolean Functions

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- In mathematics: An invertible function $f: A \rightarrow B$

$$f \text{ isomorphism}_{A,B} := \exists g : B \to A, \begin{cases} \forall b : B, (f \circ g)(b) = b \\ \forall a : A, (g \circ f)(a) = a \end{cases}$$

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• Generalization to relations needed but problematic:

$$f \text{ isomorphism}_{A,B}^{\equiv_{A},\equiv_{B}} := \exists g : B \to A, \begin{cases} \forall b : B, (f \circ g)(b) \equiv_{B} b \\ \forall a : A, (g \circ f)(a) \equiv_{A} a \end{cases}$$

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• With
$$\equiv_{all} := \mathbb{N} \times \mathbb{N}$$
 we now have
id isomorphism $\mathbb{N}_{\mathbb{N},\mathbb{N}}^{\equiv_{all},=}$

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id isomorphism $\mathbb{R}_{\mathbb{N},\mathbb{N}}^{\equiv_{all},\cdot}$

• Additional constraint: Mappings must preserve equality. $\forall a_1, a_2 \in A: a_1 \equiv_A a_2 \Rightarrow g(a_1) \equiv_B g(a_2)$ $\forall b_1, b_2 \in B: b_1 \equiv_B b_2 \Rightarrow f(b_1) \equiv_A f(b_2)$

• Use setoids and morphisms for elegant definition:

$$\begin{array}{rcl} \textit{Setoid} & := & \{(T:\textit{Type}, \ \equiv_T: T \times T) \mid \equiv_T \textit{ER}\} \\ (A, \equiv_A) \twoheadrightarrow (B, \equiv_B) & := & \{f: A \rightarrow B \mid f \text{ preserves } \equiv_B\} \end{array}$$

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• $f: (A, \equiv_A) \twoheadrightarrow (B, \equiv_B)$ and $g: (B, \equiv_B) \twoheadrightarrow (A, \equiv_A)$ form a *setoid-isomorphism* iff

$$\forall b : B, \quad (f \circ g)(b) \equiv_B b$$

$$\forall a : A, \quad (g \circ f)(a) \equiv_A a$$

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- Finite set of variables: V
- Assignments (σ): $V \rightarrow bool$
- Boolean functions (ϕ, ψ) : $(V \rightarrow bool) \rightarrow bool$

Decision trees in theory

• Based on *conditionals*:

$$(x, s, t) := (x \wedge s) \vee (\neg x \wedge t)$$

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- Defined inductively:
 - \top and \perp are decision trees.
 - (x, s, t) is a decision tree iff x variable and s, t decision trees.

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- Defined inductively:
 - \top and \perp are decision trees.
 - (x, s, t) is a decision tree iff x variable and s, t decision trees.
- Tree interpretation:

$$(x, \top, (y, \bot, \bot)) \implies \top y$$

• Prime trees are *reduced and ordered* decision trees. Let *t* be a decision tree.

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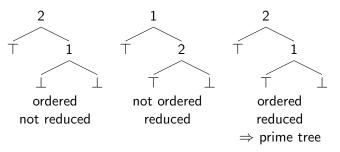
Prime trees in theory

- Prime trees are *reduced and ordered* decision trees. Let *t* be a decision tree.
 - t is reduced if none of its subtrees is of the form (x, t', t').
 - t is ordered if the variables become smaller as one descends t.

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Prime trees in theory

- Prime trees are *reduced and ordered* decision trees. Let *t* be a decision tree.
 - t is reduced if none of its subtrees is of the form (x, t', t').
 - *t* is ordered if the variables become smaller as one descends *t*.
- Examples: Let $V := \{1, 2\}$



<u>Ro</u>admap

Whatever definitions used,

- $\mathcal{B}\mathcal{F} :=$ Boolean functions
- $\mathcal{DT} :=$ Decision trees
- $\mathcal{PT} :=$ Prime trees

we will need:

- Decidable equality: $\forall t_1 t_2 : \mathcal{DT}, \{t_1 = t_2\} + \{t_1 \neq t_2\}$
- Denotational completeness: $\forall \phi : \mathcal{BF}, \{t : \mathcal{PT} \mid [t] \equiv \phi\}$
- Core result : $\forall t_1 t_2 : \mathcal{PT}, t_1 \neq t_2 \rightarrow \llbracket t_1 \rrbracket \not\equiv \llbracket t_2 \rrbracket$
- Morphisms:
 - Denotational Completeness (ex. V4) : $(\mathcal{BF}, \equiv) \rightarrow (\mathcal{PT}, =)$ $(\mathcal{PT} =) \twoheadrightarrow (\mathcal{BF} \equiv)$
 - Denotational Semantics [.]:
- Isomorphism:

$$(\mathcal{BF},\equiv)\cong(\mathcal{PT},=)$$

Version 1: The dependently typed approach Boolean functions in Coq

• Cascaded boolean functions:

 $\mathit{bool}^n \to \mathit{bool}$

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• Fixpoint nfun A n B :=

match n with

| 0 \Rightarrow B

| S n \Rightarrow A \rightarrow (nfun A n B)

end.
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 $bool^n \rightarrow bool$

• Fixpoint nfun A n B :=
match n with

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 $| S n \Rightarrow A \rightarrow (nfun A n B)$
end.

• Equivalence:

$$\phi \equiv \psi := \forall \vec{x}, \ \phi \ \vec{x} = \psi \ \vec{x}$$

Version 1: The dependently typed approach Decision trees in Coq

• Inductive $DT : nat \rightarrow Type :=$

$$| DT_0 : DT 0 | DT_1 : DT 0 | DT_I : \forall {n}, DT n \rightarrow DT n \rightarrow DT (S n) | DT_L : \forall {n}, DT n \rightarrow DT (S n).$$

• Dependency indicates number of variables the tree depends on.

Version 1: The dependently typed approach Denotational semantics and prime trees

• Denotational Semantics: Via recursion on the decision tree.

$$\begin{bmatrix} \bot \end{bmatrix} = false \\ \begin{bmatrix} \top \end{bmatrix} = true \\ \end{bmatrix} = true \\ \begin{bmatrix} (-, t_1, t_2) \end{bmatrix} = \lambda b : bool. \begin{cases} \begin{bmatrix} t_1 \end{bmatrix}, b = true \\ \end{bmatrix} t_2 \end{bmatrix}, b = false \\ \end{bmatrix} t^1 \end{bmatrix} = \lambda_- : bool. \end{bmatrix} t_2$$

• Denotational Semantics: Via recursion on the decision tree.

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- Members of *DT n* are already ordered by design.
- Thus prime trees are defined by

$$PT n := \{t : DT n \mid reduced t\}$$

Version 1: The dependently typed approach Decidable equality

• We need to write an *inversion* function ourselves: Definition $DT_{-}Inv \{n : nat\} (t : DT n) :$ match n as z return $DT z \rightarrow Type$ with $\mid O \Rightarrow fun t \Rightarrow \{t = \bot\} + \{t = \top\}$ $\mid S n' \Rightarrow fun t \Rightarrow$ $\{p : (DT n') \times (DT n') \mid t = (_, fst p, snd p)\}$ $+ \{dt : DT n' \mid t = dt^{1}\}$

end *t*.

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Decidable equality

$$\forall t_1 t_2 : DT \ n, \ \{t_1 = t_2\} + \{t_1 \neq t_2\}$$

by recursion on n.

Version 2: Recursive decision trees Recursive decision trees in Coq

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- Solution: Recursive definition instead of inductive definition

• Fixpoint DT_{rec} (n : nat) : Type :=match n with $\mid 0 \Rightarrow bool$ $\mid S n \Rightarrow (DT_{rec} n \times DT_{rec} n) + DT_{rec} n$ end.

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- Fixpoint DT_{rec} (n : nat) : Type :=match n with $\mid 0 \Rightarrow bool$ $\mid S \ n \Rightarrow (DT_{rec} \ n \times DT_{rec} \ n) + DT_{rec} \ n$ end.
- No complicated inversion function needed.

Version 1 and 2: Rest of roadmap

• Denotational Completeness

$$\forall \phi : bool^n \to bool, \{t : PT \ n \mid \llbracket t \rrbracket \equiv \phi\}$$

by recursion on number of arguments n.

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• Both straightforward.

• Copies!

• Boolean functions: true, λ_{-} .true, λ_{-} .true, ...

• Prime Trees: \top , \top^1 , \top^2 , ...

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 - Tactics inversion and injection fail to deliver.

Inversion function

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- Remedy: Recursive Decision trees.
 - injection works perfectly \Rightarrow shorter proofs.
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• Actually pretty convenient to work with.

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- Inductive SDT : Type := $| DT_0 : SDT$ $| DT_1 : SDT$ $| DT_I : nat \rightarrow SDT \rightarrow SDT \rightarrow SDT.$
- Variable on which to branch explicitly given to branching constructor.

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- Variable on which to branch explicitly given to branching constructor.
- No dependency, only one \top -tree
- Decidable equality comes for free: decide equality.

• Semantics:

$$\begin{split} \llbracket \bot \rrbracket &= \lambda_{-}. \text{ false} \\ \llbracket \top \rrbracket &= \lambda_{-}. \text{ true} \\ \llbracket (n, t_1, t_2) \rrbracket &= \lambda \sigma : (nat \to bool). \begin{cases} \llbracket t_1 \rrbracket \sigma, \ \sigma \ n = true \\ \llbracket t_2 \rrbracket \sigma, \ \sigma \ n = false \end{cases} \end{split}$$

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• Unfortunately not ordered by design:

 $SPT := \{t: SDT \mid reduced \ t \land ordered \ t\}$

 SPT not isomorphic to cascaded boolean functions while preserving meaning: true, λ_.true, ... all map to ⊤.

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- Only one constant true function : λ_{-} : (*nat* \rightarrow *bool*). *true*
- Infinitely many variables ⇒ infinite decision trees!
- Restriction to only the continuous boolean functions

 cts_n φ := "it suffices to consider the first n variables to evaluate φ".

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impossible to obtain \implies *Elim restriction*.

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• 3 possibilities to circumvent the elim restriction.

Version 3: Using the Axiom of Continuity Denotational Completeness

• Drastic solution:

- $ctsT \phi := \{n : nat \mid cts_n \phi\}$
- Axiom CTS : $\forall \phi$: BF, $ctsT \phi$.

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Plausible

$$\varphi \ \sigma := \begin{cases} true : \ \forall n, \ \sigma \ n = true \\ false : \ otherwise \end{cases} : (nat \to bool) \to Prop$$

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 Denotational completeness by recursion on the modulus of continuity given by CTS.

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- Denotational completeness by recursion on the modulus of continuity given by CTS.
- *CTS* inconsistent with *CDP* := $\forall P : Prop, \{P\} + \{\neg P\}$

$$CTS \rightarrow CDP \rightarrow False$$

Version 3: Using the Axiom of Continuity Core Result

• Direct proof of

$$\forall t_1 t_2 : SPT, \ t_1 \neq t_2 \rightarrow \llbracket t_1 \rrbracket \not \equiv \llbracket t_2 \rrbracket$$

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via induction is **HUGE** : 9 cases!

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via induction is **HUGE** : 9 cases!

• Use size induction on pairs of decision trees.

• Divide proof into case analysis

•
$$|t_1| + |t_2| = 0 \rightarrow (t_1 = \top \lor t_1 = \bot) \land (t_2 = \top \lor t_2 = \bot).$$

• $|t_1| + |t_2| = m + 1 \rightarrow \begin{cases} t_1 = (n, t, t') \land n \notin t_2 \\ n \notin t_1 \land t_2 = (n, t, t') \\ t_1 = (n, t'_1, t''_1) \land t_2 = (n, t'_2, t''_2) \end{cases}$

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and main proof:

• CTS too drastic.



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- Restriction to continuous boolean functions

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• Equivalence on BF_{cts} := Equivalence of underlying functions.

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- Prove denotational completeness as proposition

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$$\forall \phi : BF_{cts}, \exists t : SPT, [[t]] \equiv \phi$$

Prove core result like before

$$\forall t_1 t_2 : SPT, \ t_1 \neq t_2 \rightarrow \llbracket t_1 \rrbracket \not \equiv \llbracket t_2 \rrbracket$$

Version 4: Using the Axiom of Description A morphism from (BF_{cts}, \equiv) to (SPT,=)

• From denotational completeness and core result derive that there is a unique *SPT* for every *BF_{cts}*:

$$\forall \phi : BF_{cts}, \exists !t : SPT, \llbracket t \rrbracket \equiv \phi$$

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• From denotational completeness and core result derive that there is a unique *SPT* for every *BF_{cts}*:

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• Turn this proof into a mapping using Axiom of Description:

 $\forall (T: Type)(P: T \rightarrow Prop), \ (\exists !t: T, P \ t) \rightarrow \{t: T \mid P \ t\}$

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• We want to use $[\![\cdot]\!]$



Version 4: Using the Axiom of Description A morphism from (SPT,=) to (BF_{cts}, \equiv)

- We want to use $\llbracket \cdot \rrbracket$
- Prove that decision trees describe continuous functions

```
\forall t: SDT, \ cts \llbracket t \rrbracket
```

by writing a function that determines a modulus of continuity

 $\forall t: SDT, \ ctsT \llbracket t \rrbracket$

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- We want to use $\llbracket \cdot \rrbracket$
- Prove that decision trees describe continuous functions

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\forall t : SDT, \ cts \llbracket t \rrbracket
```

by writing a function that determines a modulus of continuity

```
\forall t : SDT, \ ctsT \llbracket t \rrbracket
```

• Modulus of continuity is largest variable in the tree.

• Pair boolean functions with their modulus of continuity.

$$BF_{ctsT} := \{\phi : BF \& cts_T \phi\}$$

• Equivalence:

$$(\phi, n) \equiv (\psi, m) := \phi \equiv \psi$$

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• Pair boolean functions with their modulus of continuity.

$$BF_{ctsT} := \{\phi : BF \& cts_T \phi\}$$

Equivalence:

$$(\phi, n) \equiv (\psi, m) := \phi \equiv \psi$$

Denotational Completeness

$$\forall (\phi, n) : BF_{ctsT}, \ \{t : SPT \mid \llbracket t \rrbracket \equiv \phi\}$$

by recursion on modulus of continuity n.

• Core result as before.

- No copies!
- More work:
 - Ordering
 - $n \in t$
 - Lemmas relating orderedness and variable occurrences.

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• Axioms (Versions 3 and 4)!

• Goal: Canonical representation for boolean functions

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- Goal: Canonical representation for boolean functions
- A representative should have the same meaning as the function it describes

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- Goal: Canonical representation for boolean functions
- A representative should have the same meaning as the function it describes

• Setoid-isomorphism not meaning preserving!

• Definition of *representative* of boolean functions:

$$\begin{cases} T : Type \\ =_T : T \to T \to Prop \\ \llbracket \cdot \rrbracket : T \to \mathcal{BF} \\ ER : =_T \text{ is equivalence relation} \\ P : \forall t_1 t_2 : T, t_1 =_T t_2 \to \llbracket t_1 \rrbracket \equiv_{\mathcal{BF}} \llbracket t_2 \rrbracket \end{cases}$$

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• Meaning preserving morphisms:

$$\left\{\begin{array}{ll} \varrho & : \ T \to T' \\ EP & : \ \forall t_1 t_2 : T, \ t_1 =_T t_2 \to \varrho \ t_1 =_{T'} \varrho \ t_2 \\ MP & : \ \forall t : T, \ \llbracket t \rrbracket_T \equiv_{\mathcal{BF}} \llbracket \varrho \ t \rrbracket_{T'} \end{array}\right\}$$

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 Used setoids are representatives, morphisms are meaning preserving

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