### Undecidability of Semi-unification on a Napkin

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## Semi-unification

### Definition (Terms $\mathbb{T}$ )

 $\mathbb{T} \ni \sigma, \tau ::= \alpha \mid \sigma \to \tau \quad \text{where } \alpha \text{ ranges over variables } \mathbb{V}$ 

• Semi-unification  $\sim$  first-order unification combined with matching

### Problem (Semi-unification)

Given inequalities  $\mathcal{I} = \{\sigma_1 \leq \tau_1, \dots, \sigma_n \leq \tau_n\}$ , is there a substitution  $\varphi : \mathbb{V} \to \mathbb{T}$  such that for each inequality  $(\sigma \leq \tau) \in \mathcal{I}$ there is a substitution  $\psi : \mathbb{V} \to \mathbb{T}$  such that  $\psi(\varphi(\sigma)) = \varphi(\tau)$ ?

Theorem ([Kfoury, Tiuryn, and Urzyczyn 1993a])

Semi-unification is undecidable.

## Semi-unification Occurrences

- Type inference in polymorphic functional programming [Leiß 1989; Kfoury, Tiuryn, and Urzyczyn 1993b; Henglein 1993]
- Type inference in polymorphic logic programming [Mycroft and O'Keefe 1984]
- System F type checking [Wells 1999]
- Loop detection in term rewriting [Purdom 1987]
- Program flow analysis [Fähndrich, Rehof, and Das 2000]
- Natural language processing [Dörre and Rounds 1990]

## Semi-unification Example

Example (Composed Iteration)
• iter2 :: Nat -> (a -> b) -> (b -> a) -> a -> a
• iter2 0 f g x = x
• iter2 1 f g x = g (f x)
• iter2 2 f g x = g (f (g (f x)))
In Haskell
iter2 0 f g x = x iter2 n f g x = g (iter2 (n-1) g f (f x))
has type
iter2 :: Nat -> (a -> a) -> (a -> a) -> a -> a
where types of f and g are unified.

## Semi-unification Example

### Example (Composed Iteration)

iter2 0 f g x = x iter2 n f g x = g (iter2 (n-1) g f (f x))

Parametric polymorphism: monomorphic recursive calls
 → find substitution φ such that

$$\begin{split} \varphi(\mathsf{Nat} \to (\alpha \to \beta) \to (\beta \to \alpha) \to \alpha \to \alpha) \\ = \varphi(\mathsf{Nat} \to (\beta \to \alpha) \to (\alpha \to \beta) \to \beta \to \beta) \\ \rightsquigarrow \varphi = \{\alpha \rightleftharpoons \mathsf{a}, \beta \rightleftharpoons \mathsf{a}\} \end{split}$$

## Recursive polymorphism: instantiated recursive calls → find substitutions φ, ψ such that

 $\psi(\varphi(\mathsf{Nat} \to (\alpha \to \beta) \to (\beta \to \alpha) \to \alpha \to \alpha))$ =  $\varphi(\mathsf{Nat} \to (\beta \to \alpha) \to (\alpha \to \beta) \to \beta \to \beta)$  $\rightsquigarrow \varphi = \{\alpha \Rightarrow \alpha, \beta \Rightarrow \beta\}, \ \psi = \{\alpha \Rightarrow \beta, \beta \Rightarrow \alpha\}$ Different  $\psi$  for individual recursive calls  $\rightsquigarrow$  semi-unification

## Semi-unification Undecidability

### Original Proof Synopsis.

**Turing machine immortality** [Hooper 1966] (is there an non-terminating configuration?)

## Section 2 States - States -

- Symmetric intercell Turing machine uniform boundedness (as above; returning to potential past configurations)
- Summa Strain Strain
- $\leq$  Semi-unification

Uses excluded middle and König's lemma

## Semi-unification Undecidability

### New Proof Synopsis.

**Turing machine immortality** [Hooper 1966] (is there an non-terminating configuration?)

- Stack machine uniform boundedness (is the number of reachable configurations uniformly bounded?)
- $\leq$  Semi-unification
  - First step uses fan theorem (Brouwer's intuitionism)
  - Second step is fully constructive (axiom-free Coq, 1500 loc)

## Simple Stack Machine

### Definition (Simple Stack Machine)

**Instruction:**  $ap \longrightarrow qb$  or  $pb \longrightarrow aq$ 

where  $\pmb{p},\pmb{q}$  are states and  $\pmb{a},\pmb{b}\in\{\pmb{0},\pmb{1}\}$  are symbols

Simple stack machine: list of instructions  $\mathcal{M}$ 

### Configuration: spit

where  $\pmb{p}$  is a state and  $\pmb{s}, \pmb{t} \in \{\pmb{0}, \pmb{1}\}^*$  are words

### Step relation:

 $\begin{array}{l} sa|p|t \longrightarrow_{\mathcal{M}} s|q|bt \text{ if } (ap \longrightarrow qb) \in \mathcal{M} \\ s|p|bt \longrightarrow_{\mathcal{M}} sa|q|t \text{ if } (pb \longrightarrow aq) \in \mathcal{M} \end{array}$ 

### ullet Simple stack machine $\sim$ space-bounded intercell Turing machine

### Problem (Uniform Boundedness)

Given a simple stack machine  $\mathcal{M}$ , is there an  $\mathbf{n} \in \mathbb{N}$  such that for any configuration  $\mathbf{X}$  we have  $|\{\mathbf{Y} \mid \mathbf{X} \longrightarrow_{\mathcal{M}}^{*} \mathbf{Y}\}| \leq \mathbf{n}$ ?

## Simple Stack Machine Properties

- Mechanization-friendly (specification 30 loc)
- No infinite tape (linear automaton)
- Decidable reachability and termination (every run operates in bounded space)

## Simple Semi-unification

### Definition (Simple Constraint)

Simple constraint:  $a |\alpha| \epsilon \doteq \epsilon |\beta| b$ where  $\alpha \in \mathbb{V}$  and  $a, b \in \{0, 1\}$ Model:  $(\varphi, \psi_0, \psi_1) \models a |\alpha| \epsilon \doteq \epsilon |\beta| b$  if either b = 0 and  $\psi_a(\varphi(\alpha)) \rightarrow \tau = \varphi(\beta)$  for some  $\tau$ b = 1 and  $\sigma \rightarrow \psi_a(\varphi(\alpha)) = \varphi(\beta)$  for some  $\sigma$ 

### Definition (Simple Semi-unification)

Given a finite set C of simple constraints, are there substitutions  $\varphi, \psi_0, \psi_1 : \mathbb{V} \to \mathbb{T}$  such that for all constraints  $C \in C$  we have  $(\varphi, \psi_0, \psi_1) \models C$ ?

• Undecidable fragment of semi-unification

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{\mathbf{0}p \longrightarrow p\mathbf{1}\}$ 

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{0p \longrightarrow p1\}$ 

#### 000*|p*|€

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{\mathbf{0}p \longrightarrow p\mathbf{1}\}$ 

 $000|p|\epsilon \longrightarrow_{\mathcal{M}} 00|p|1$ 

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{\mathbf{0}p \longrightarrow p\mathbf{1}\}$ 

 $000|p|\epsilon \longrightarrow_{\mathcal{M}} 00|p|1 \longrightarrow_{\mathcal{M}} 0|p|11$ 

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{\mathbf{0}p \longrightarrow p\mathbf{1}\}$ 

 $000|p|\epsilon \longrightarrow_{\mathcal{M}} 00|p|1 \longrightarrow_{\mathcal{M}} 0|p|11 \longrightarrow_{\mathcal{M}} \epsilon|p|111$ 

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{ 0p \longrightarrow p1 \}$ 

 $000|p|\epsilon \longrightarrow_{\mathcal{M}} 00|p|1 \longrightarrow_{\mathcal{M}} 0|p|11 \longrightarrow_{\mathcal{M}} \epsilon|p|111$ 

 $\sim 0^{n} |\mathbf{p}| \epsilon$  reaches n + 1 distinct configurations  $\sim n$  no *uniform* bound on number of reachable configurations

Example (Not Uniformly Bounded Stack Machine)  $\mathcal{M} = \{\mathbf{0}p \longrightarrow p\mathbf{1}\}$ 

 $000|p|\epsilon \longrightarrow_{\mathcal{M}} 00|p|1 \longrightarrow_{\mathcal{M}} 0|p|11 \longrightarrow_{\mathcal{M}} \epsilon|p|111$ 

 $\sim 0^{n} |\mathbf{p}| \epsilon$  reaches n + 1 distinct configurations  $\sim no$  uniform bound on number of reachable configurations

•  $0p \longrightarrow p1 \rightsquigarrow 0|p|\epsilon \doteq \epsilon|p|1$ 

Example (Unsolvable Constraints)

 $\mathcal{C} = \{\mathbf{0} | p | \boldsymbol{\epsilon} \doteq \boldsymbol{\epsilon} | p | \mathbf{1}\}$ 

• 
$$\sigma \rightarrow \psi_0(\varphi(p)) = \varphi(p)$$

 $\rightsquigarrow$  no model

Example (Uniformly Bounded Stack Machine)

 $\mathcal{M} = \{\mathbf{0} p \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1} p, \mathbf{1} p \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0} p\}$ 

## Uniformly Bounded Example Example (Uniformly Bounded Stack Machine)

$$\mathcal{M} = \{ \begin{array}{c} \mathbf{0}\rho \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1}\rho, \mathbf{1}\rho \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0}\rho \\ \mathbf{0}|\rho|\epsilon \end{array} \}$$

# Uniformly Bounded Example Example (Uniformly Bounded Stack Machine) $\mathcal{M} = \{ \begin{array}{l} 0p \longrightarrow q1, q1 \longrightarrow 1p, 1p \longrightarrow q0, q0 \longrightarrow 0p \\ 0 | p| \epsilon \longrightarrow_{\mathcal{M}} \epsilon | q| 1 \end{array}$

Example (Uniformly Bounded Stack Machine)

$$\mathcal{M} = \{ \begin{array}{c} \mathbf{0}p \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1}p, \mathbf{1}p \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0}p \\ \mathbf{0}|p| \epsilon \longrightarrow_{\mathcal{M}} \epsilon |q|\mathbf{1} \longrightarrow_{\mathcal{M}} \mathbf{1}|p| \epsilon \end{array}$$

## Uniformly Bounded Example Example (Uniformly Bounded Stack Machine) $\mathcal{M} = \{\mathbf{0}p \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1}p, \mathbf{1}p \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0}p\}$

$$0|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon |q|1 \longrightarrow_{\mathcal{M}} 1|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon |q|0$$

Example (Uniformly Bounded Stack Machine)

$$\mathcal{M} = \{ \begin{array}{c} \mathbf{0}p \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1}p, \mathbf{1}p \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0}p \\ \mathbf{0}|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|\mathbf{1} \longrightarrow_{\mathcal{M}} \mathbf{1}|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|\mathbf{0} \longrightarrow_{\mathcal{M}} \mathbf{0}|p|\epsilon \end{array}$$

# Uniformly Bounded Example Example (Uniformly Bounded Stack Machine) $\mathcal{M} = \{ \begin{array}{l} 0p \longrightarrow q1, q1 \longrightarrow 1p, 1p \longrightarrow q0, q0 \longrightarrow 0p \} \\ 0|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|1 \longrightarrow_{\mathcal{M}} 1|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|0 \longrightarrow_{\mathcal{M}} 0|p|\epsilon \\ \\ \Rightarrow \text{ any configuration reaches at most 4 distinct configurations} \end{cases}$

Example (Uniformly Bounded Stack Machine)

$$\mathcal{M} = \{\mathbf{0}p \longrightarrow q\mathbf{1}, q\mathbf{1} \longrightarrow \mathbf{1}p, \mathbf{1}p \longrightarrow q\mathbf{0}, q\mathbf{0} \longrightarrow \mathbf{0}p\}$$

 $0|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|1 \longrightarrow_{\mathcal{M}} 1|p|\epsilon \longrightarrow_{\mathcal{M}} \epsilon|q|0 \longrightarrow_{\mathcal{M}} 0|p|\epsilon$ 

 $\rightsquigarrow$  any configuration reaches at most  ${\bf 4}$  distinct configurations

### Example (Solvable Constraints)

$$\mathcal{C} = \{\mathbf{0} | p| \epsilon \doteq \epsilon | q| \mathbf{1}, \mathbf{1} | p| \epsilon \doteq \epsilon | q| \mathbf{1}, \mathbf{1} | p| \epsilon \doteq \epsilon | q| \mathbf{0}, \mathbf{0} | p| \epsilon \doteq \epsilon | q| \mathbf{0} \}$$

- $\sigma \to \psi_0(\varphi(p)) = \varphi(q)$
- $\sigma \rightarrow \psi_1(\varphi(p)) = \varphi(q)$
- $\psi_1(\varphi(p)) \to \tau = \varphi(q)$
- $\psi_0(\varphi(p)) \rightarrow \tau = \varphi(q)$

 $\rightsquigarrow$  model

$$\varphi(\mathbf{p}) = \alpha$$
$$\varphi(\mathbf{q}) = \beta \rightarrow \beta$$
$$\psi_0(\alpha) = \psi_1(\alpha) = \beta$$

## Reduction Soundness

### Definition (Machine Encoding)

Given simple stack machine  $\mathcal{M}$ , define  $\mathcal{C} = \{ a | p | \epsilon \doteq \epsilon | q | b \mid (ap \longrightarrow qb) \in \mathcal{M} \text{ or } (qb \longrightarrow ap) \in \mathcal{M} \}$ 

Definition  $(\zeta)$ 

$$\zeta(s|p|t) = \begin{cases} \zeta(s|p|t0) \to \zeta(s|p|t1) & \text{if } s|p|t \text{ is narrow} \\ \alpha_{[s|p|t]} & \text{otherwise} \end{cases}$$

where narrowness is decidable and  $\left[\cdot\right]$  is a total and computable

#### Lemma (Reduction Soundness)

If  $\mathcal{M}$  is uniformly bounded, then  $(\varphi, \psi_0, \psi_1) \models \mathcal{C}$  where

 $\varphi(p) = \zeta(\epsilon | p|\epsilon) \qquad \psi_0(\alpha_{s|p|t}) = \zeta(0s|p|t) \qquad \psi_1(\alpha_{s|p|t}) = \zeta(1s|p|t)$ 

## **Reduction Completeness**

### Definition (Machine Encoding)

Given simple stack machine  $\mathcal{M}$ , define

$$\mathcal{C} = \{ a_{!}p_{!}\epsilon \doteq \epsilon_{!}q_{!}b \mid (ap \longrightarrow qb) \in \mathcal{M} \text{ or } (qb \longrightarrow ap) \in \mathcal{M} \}$$

#### Lemma

$$X \longrightarrow^*_{\mathcal{M}} Y$$
 and  $(arphi, \psi_0, \psi_1) \models \mathcal{C}$  implies  $(arphi, \psi_0, \psi_1) \models X \doteq Y$ 

#### Remark

Size of the syntax tree of  $\varphi(p)$  uniformly bounds reachable configuration space from state p.

### Lemma (Reduction Completeness)

If  $(\varphi, \psi_0, \psi_1) \models C$ , then  $\mathcal{M}$  is uniformly bounded.

## Contribution

- Intuitionistic (in sense of Brouwer) Turing reduction from Turing machine immortality to simple stack machine uniform boundedness
- Fully constructive many-one reduction from simple stack machine uniform boundedness to semi-unification
  - $\blacktriangleright$  simple and direct via  $oldsymbol{\zeta}$
  - mechanized (axiom-free Coq)
    (specification 100 loc, argument 1400 loc)
    https://github.com/uds-psl/2020-fscd-semi-unification

Ongoing Work

### Mechanized reduction from the **Turing machine halting problem** to **semi-unification**

- comprehensive (current mechanization starts with boundedness)
- many-one

(current proof requires Turing reductions)

axiom-free

(current proof requires fan theorem)

 part of the Coq library of Undecidability Proofs https://github.com/uds-psl/coq-library-undecidability

## **Ongoing Work**

Mechanized reduction from the **Turing machine halting problem** to **semi-unification** 

comprehensive

(current mechanization starts with boundedness)

- many-one (current proof requires Turing reductions)
- axiom-free

(current proof requires fan theorem)

part of the Coq library of Undecidability Proofs
 https://github.com/uds-psl/coq-library-undecidability

## Thank You

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## **Backup Slides**

## Constraint-based Semi-unification

### Definition (Substitution Composition)

For substitutions  $\psi_0,\psi_1:\mathbb{V} o\mathbb{T}$  and word  $m{v}\in\{0,1\}^*$  define

$$\psi_{\epsilon}(\sigma) = \sigma$$
  $\psi_{\nu 0}(\sigma) = \psi_{\nu}(\psi_0(\sigma))$   $\psi_{\nu 1}(\sigma) = \psi_{\nu}(\psi_1(\sigma))$ 

$$\begin{array}{l} \text{Definition (Path Function)} \\ \text{For } \textbf{\textit{w}} \in \{0,1\}^* \text{ define} \\ \pi_{\epsilon}(\sigma) = \sigma \qquad \pi_{0w}(\sigma \to \tau) = \pi_w(\sigma) \qquad \pi_{1w}(\sigma \to \tau) = \pi_w(\tau) \end{array}$$

### Definition (Constraint)

Constraint:  $s_{|\alpha|}t \doteq v_{|\beta|}w$ where  $\alpha, \beta \in \mathbb{V}$  and  $s, t, v, w \in \{0, 1\}^*$ Model:  $(\varphi, \psi_0, \psi_1) \models (s_{|\alpha|}t \doteq v_{|\beta|}w)$  if  $\pi_t(\psi_s(\varphi(\alpha)) = \pi_w(\psi_v(\varphi(\beta)))$ 

## Narrow Configuration, Representative

### Definition (Joinable Configurations)

Configurations X, Y are *joinable* in  $\mathcal{M}$ , if  $X \longrightarrow_{\mathcal{M}}^{*} Z \longleftarrow_{\mathcal{M}}^{*} Y$  for some configuration Z.

### Definition (Narrow Configuration)

A configuration  $\boldsymbol{X}$  is *narrow* in  $\boldsymbol{\mathcal{M}}$ ,

if **X** and  $s_{|p|\epsilon}$  are joinable in  $\mathcal{M}$  for some state p and a word  $s \in \mathbb{B}^*$ .

### Definition (Representative $[X]_{\mathcal{M}}$ )

The *representative* of X in  $\mathcal{M}$  is the lexicographically smallest configuration Y such that X and Y are joinable in  $\mathcal{M}$ .

- Joinability is decidable
- Narrowness is decidable
- Representative is computable