

Formula Convention and Linear Proofs

A formula $\alpha = \beta$ is a term of type \mathbb{B} .

An equation $\alpha = \beta$ may be written as $\alpha \Delta \beta$

This is just notational sugar.

It greatly improves the readability of entailment laws and proofs, as you will see from the following examples.

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Entailment Laws for BA

Sub	$\alpha \vdash \alpha [k_1 = t]$	
Alpha	$\alpha \vdash \alpha [x := \gamma]$	
And	$x \wedge y \vdash \frac{\text{BA}}{\text{A}}$, $x, y \vdash \text{BA}$	$x = y \vdash \frac{\text{BA}}{\text{A}}$, $\bar{x} = \bar{y}$
Or	$x \vdash \frac{\text{BA}}{\text{A}}$, $x \vee y$	
Equi	$x \leftrightarrow y \vdash \frac{\text{BA}}{\text{A}}$, $x \rightarrow y, y \rightarrow x$	$x \leftrightarrow y \vdash \frac{\text{BA}}{\text{A}}$, $x \rightarrow y, y \rightarrow x$
MP	$x \rightarrow y, x \vdash \frac{\text{BA}}{\text{A}}$, y	$x \rightarrow y, x \vdash \frac{\text{BA}}{\text{A}}$, y
GR	$x \rightarrow y \vdash \frac{\text{BA}}{\text{A}}$, $x = x \wedge y \vdash \frac{\text{BA}}{\text{A}}$, $y = y \vee x$	$x = \bar{y} \vdash \frac{\text{BA}}{\text{A}}$, $x \vee y, \frac{\text{BA}}{\text{A}}$
UoC		

Entailment Laws for HB and Duality

BCA	$\alpha, \beta \vdash H \wedge \gamma$	
Ded	$A \vdash \alpha \rightarrow \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$	$A \vdash \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$
		$A \vdash \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$
Dual	$\alpha \rightarrow \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$	$A \vdash \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$
		$A \vdash \epsilon \Leftrightarrow \alpha \vdash^A \epsilon$

Entailment Laws for BQ

$$\begin{array}{l} \text{HT} \quad \forall A \frac{\exists a}{\exists x} \\ \text{FT} \quad \frac{\exists A}{\exists x} \end{array}$$

$$\text{Gen} \quad \frac{\exists A}{\exists x}$$

Conversion Proof: Shows $E \frac{A}{\exists x. A} \vdash \exists x. A$
 by a sequence $\alpha_1 = \alpha_2 = \alpha_3 = \dots = \alpha_n$
 where each step $\alpha_i = \alpha_{i+1}$ represents
 one or several conversions.

Entailment Proof: Shows $E_n \frac{A}{E_1}$
 by a sequence $E_1 \rightarrow E_2 \rightarrow E_3 \rightarrow \dots \rightarrow E_n$,
 where $E_{i+1} \frac{A}{E_i}$ for each step by simple
 arguments. Can mix in $E_i \vdash E_{i+1}$ and
 conversion steps.

Linear Proofs

Formerly called
remitting proofs

We have seen
many examples

Example: Linear Entailment Proof for Cantor's Law

Claim: $\exists x \vdash \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r$

$$\begin{aligned} & \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \exists A \end{aligned}$$

Proof:

$$\begin{aligned} & \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \frac{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ &= \exists A \end{aligned}$$

Justification:

$$\begin{aligned} & \alpha_1 = \alpha_2 \vdash \alpha_3 \vdash \alpha_4 \vdash \alpha_5 \vdash \alpha_6 = r \\ & \exists x \vdash \alpha_2 \quad \alpha_2 \frac{\exists y}{\exists x \exists y} \quad \alpha_3 \frac{\exists z}{\exists x \exists y \exists z} \quad \alpha_4 \frac{\exists u}{\exists x \exists y \exists z \exists u} \quad \alpha_5 \frac{\exists v}{\exists x \exists y \exists z \exists u \exists v} \quad \alpha_6 \frac{\forall r \leftrightarrow s r}{\exists x \exists y \exists z \exists u \exists v \forall r \leftrightarrow s r} \\ & \text{Hence } \exists x \vdash \alpha_1 = r. \end{aligned}$$