

# **Constraint Programming**

Marco Kuhlmann & Guido Tack  
Lecture 2



# **Today: History and Practice**

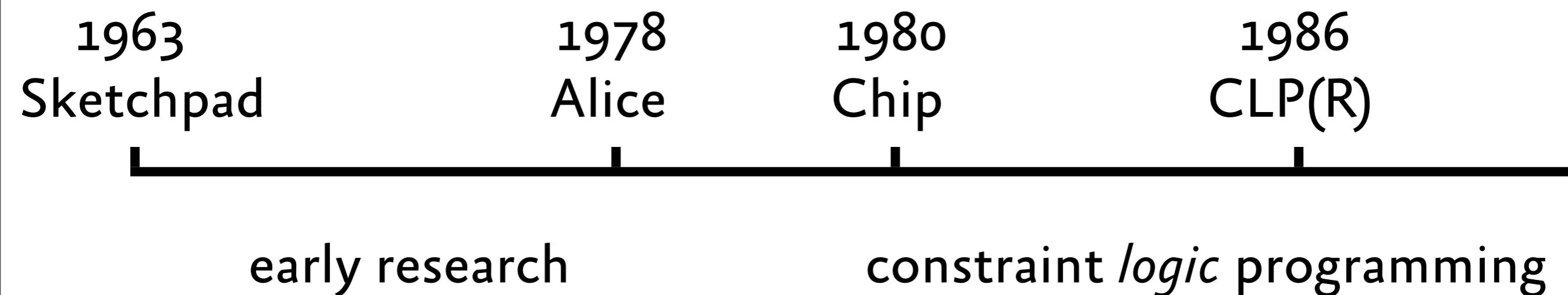
# History and Practice

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- **Part I: Short historical overview**
  - where does CP come from?
- **Part II: Constraint Programming with Gecode/J**
  - give you intuition about what's under the hood
  - scratch all topics we will discuss in this course

# Historical notes

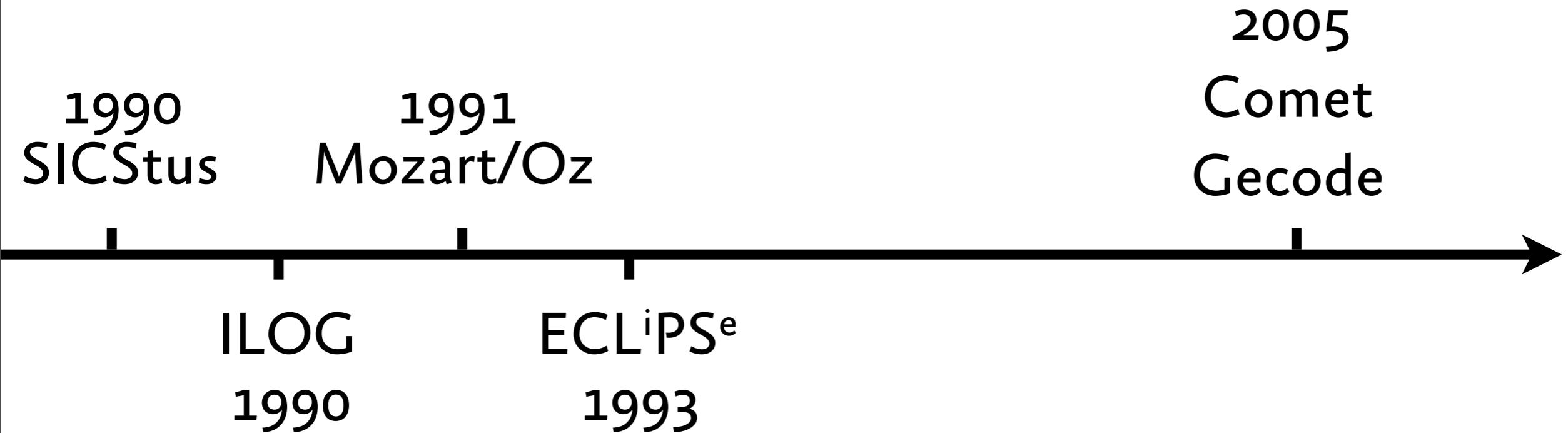
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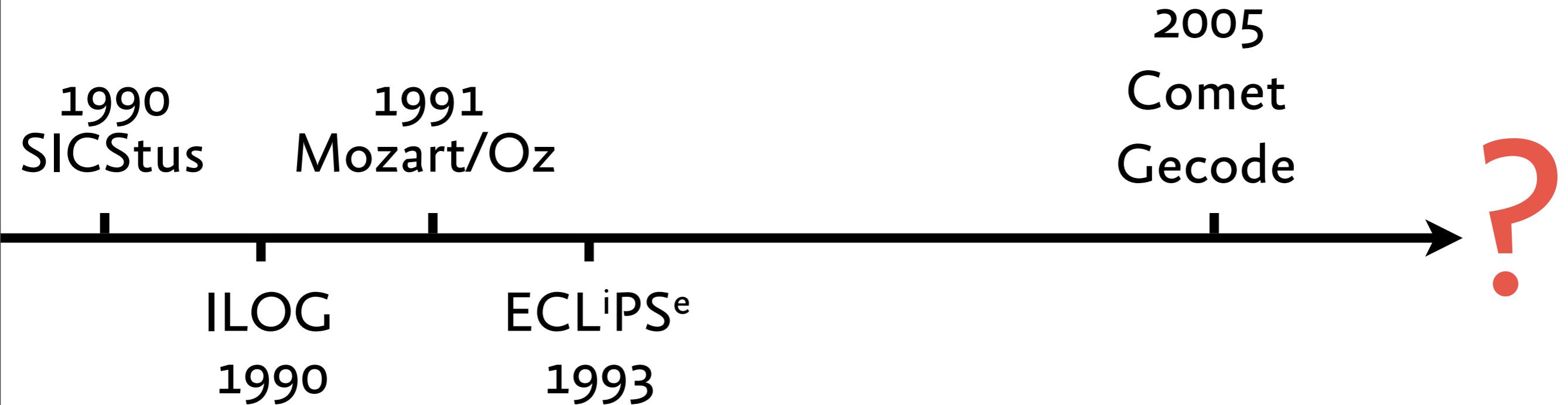
# Historical notes

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# Historical notes

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# Logic Programming

---

```
foo(a) .
```

```
foo(b) .
```

```
g(X) :- X=[Y, Z], foo(Y), foo(Z) .
```

# Logic Programming

---

```
foo(a) .
```

```
foo(b) .
```

```
g(X) :- X=[Y, Z], foo(Y), foo(Z) .
```

```
| ?- g(X) .
```

```
X = [a,a] ? ;
```

```
X = [a,b] ? ;
```

```
X = [b,a] ? ;
```

```
X = [b,b]
```

# Constraint Logic Programming

---

```
foo(X) :- fd_domain(X, 1, 3).  
g(Y,Z) :- foo(Y), foo(Z), Y #< Z,  
          fd_labeling([Y,Z]).
```

# Constraint Logic Programming

---

```
foo(X) :- fd_domain(X, 1, 3).  
g(Y,Z) :- foo(Y), foo(Z), Y #< Z,  
          fd_labeling([Y,Z]).
```

```
| ?- g(X,Y).
```

```
X = 1
```

```
Y = 2 ? ;
```

```
X = 1
```

```
Y = 3 ? ;
```

```
X = 2
```

```
Y = 3
```

# Constraint Logic Programming

---

```
foo(X) :- fd_domain(X, 1, 3).  
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```

```
Y = 3
```

Model:

constraint program

=

logic program

=

logical formula

# Constraint Logic Programming

---

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```
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```

```
Y = 3
```

Languages/Systems:

GNU Prolog, BProlog, SICStus  
Prolog, ECL<sup>i</sup>PS<sup>e</sup>

# Concurrent Constraint Programming

---

# Concurrent Constraint Programming

---

- Von-Neumann architecture: store *values*
  - operations: read and write

# Concurrent Constraint Programming

---

- Von-Neumann architecture: store *values*
  - operations: read and write
- cc architecture: store *constraints*
  - operations: ask and tell
  - communication through variables

# Concurrent Constraint Programming

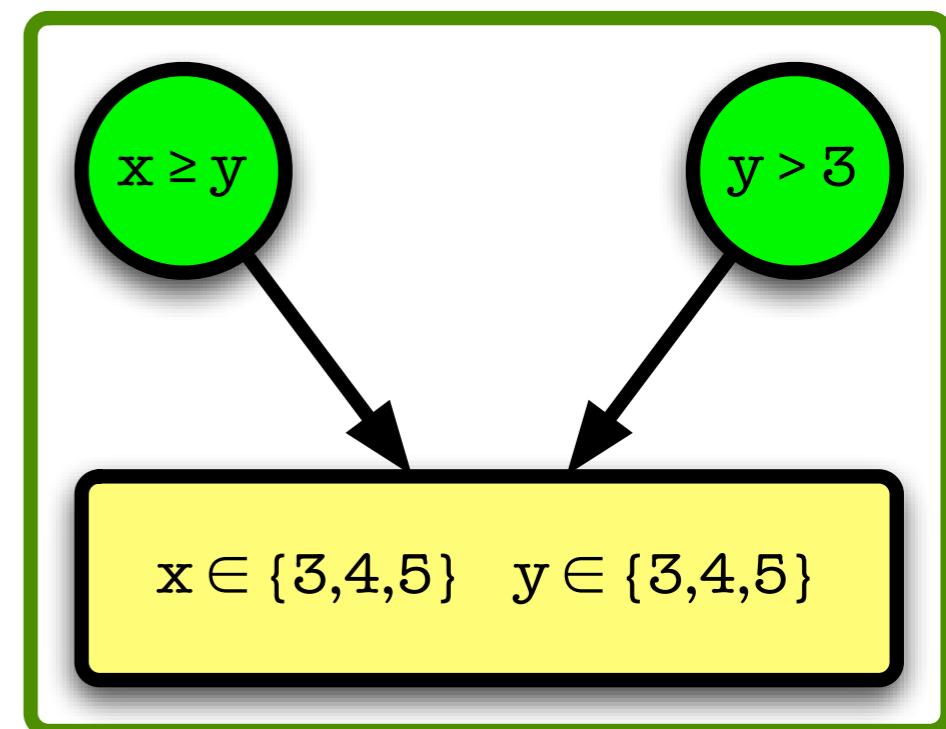
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- Von-Neumann architecture: store *values*
  - operations: read and write
- cc architecture: store *constraints*
  - operations: ask and tell
  - communication through variables
- Languages/systems:
  - cc(FD), AKL, Mozart/Oz

# Concurrent Constraint Programming

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- Von-Neumann architecture: store *values*
  - operations: read and write
- cc architecture: store *constraints*
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  - communication through variables
- Languages/systems:
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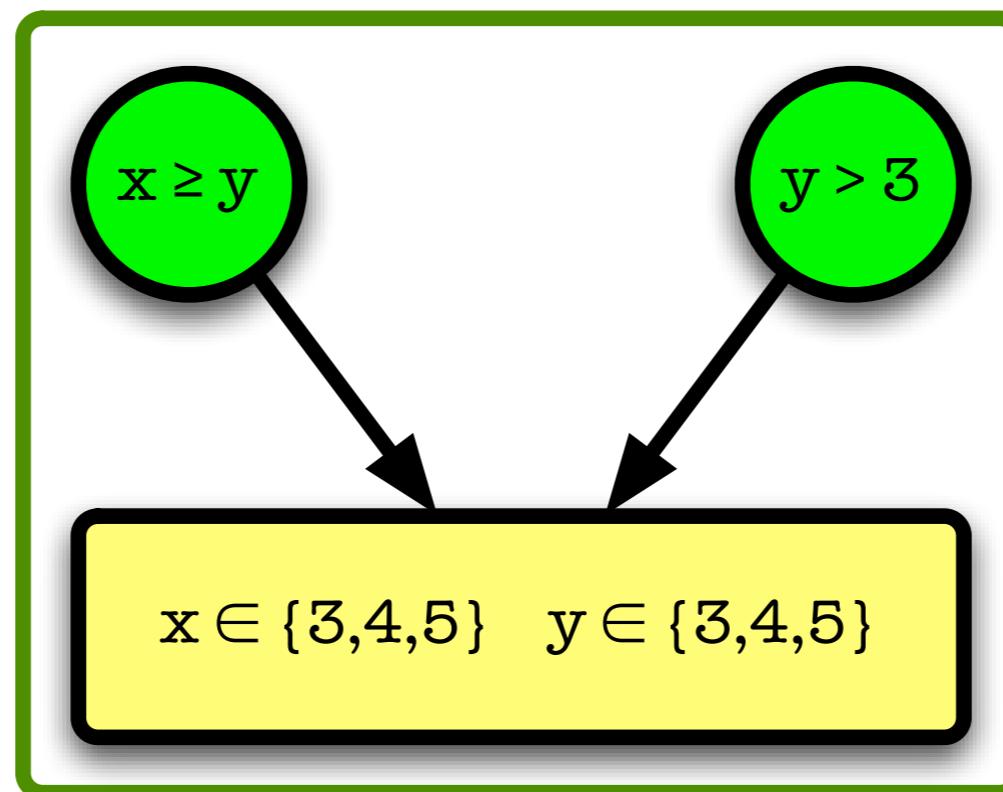
# Constraint Programming with Gecode/J

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- Quick reminder of last lecture
- Walk-through for *Send More Money*
- Some modeling techniques
- Presentation of first graded lab

# Computation Space

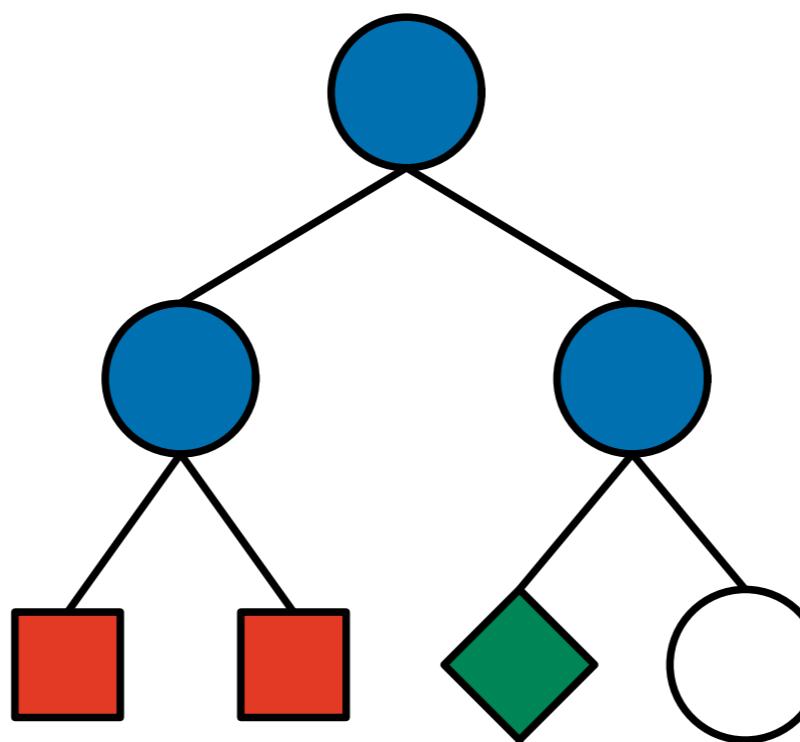
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constraint store with connected propagators

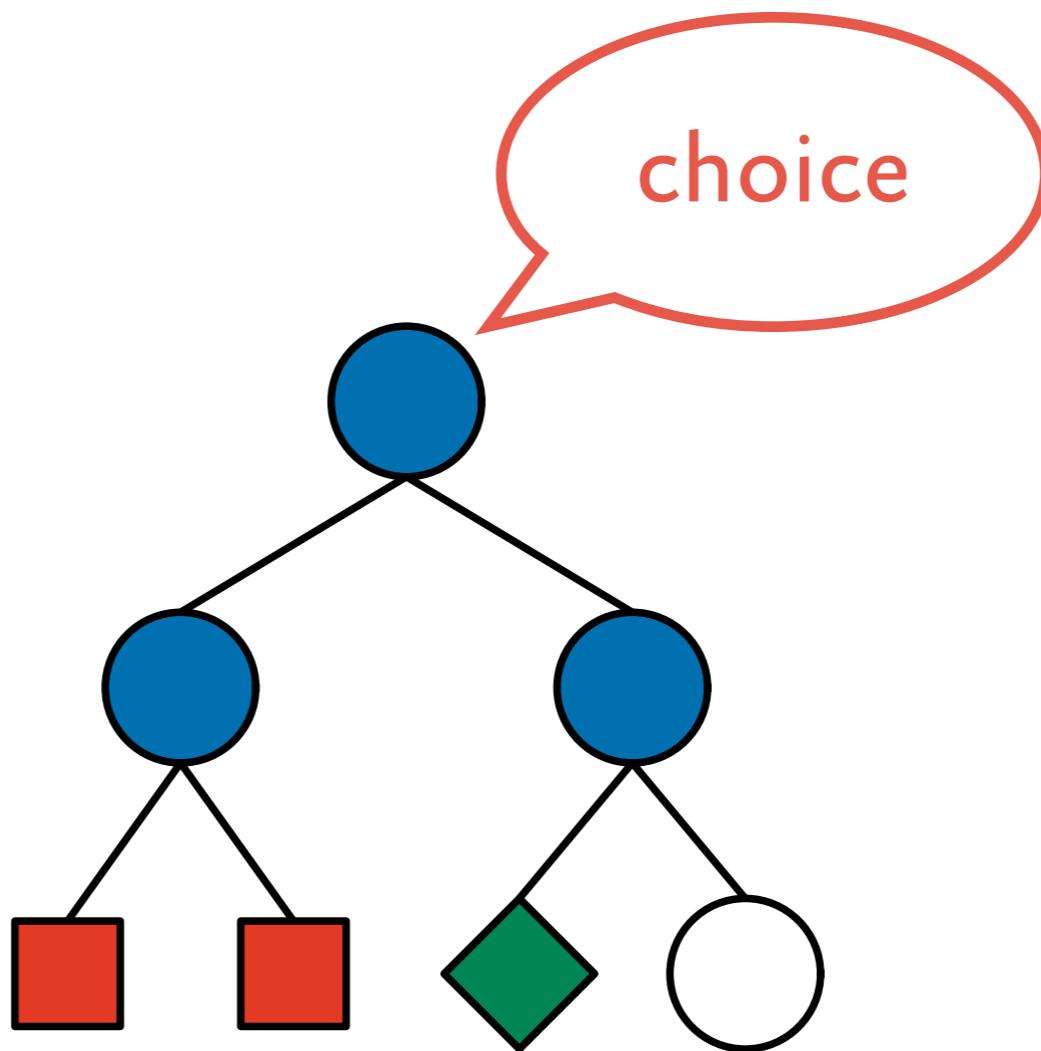
# Search

---



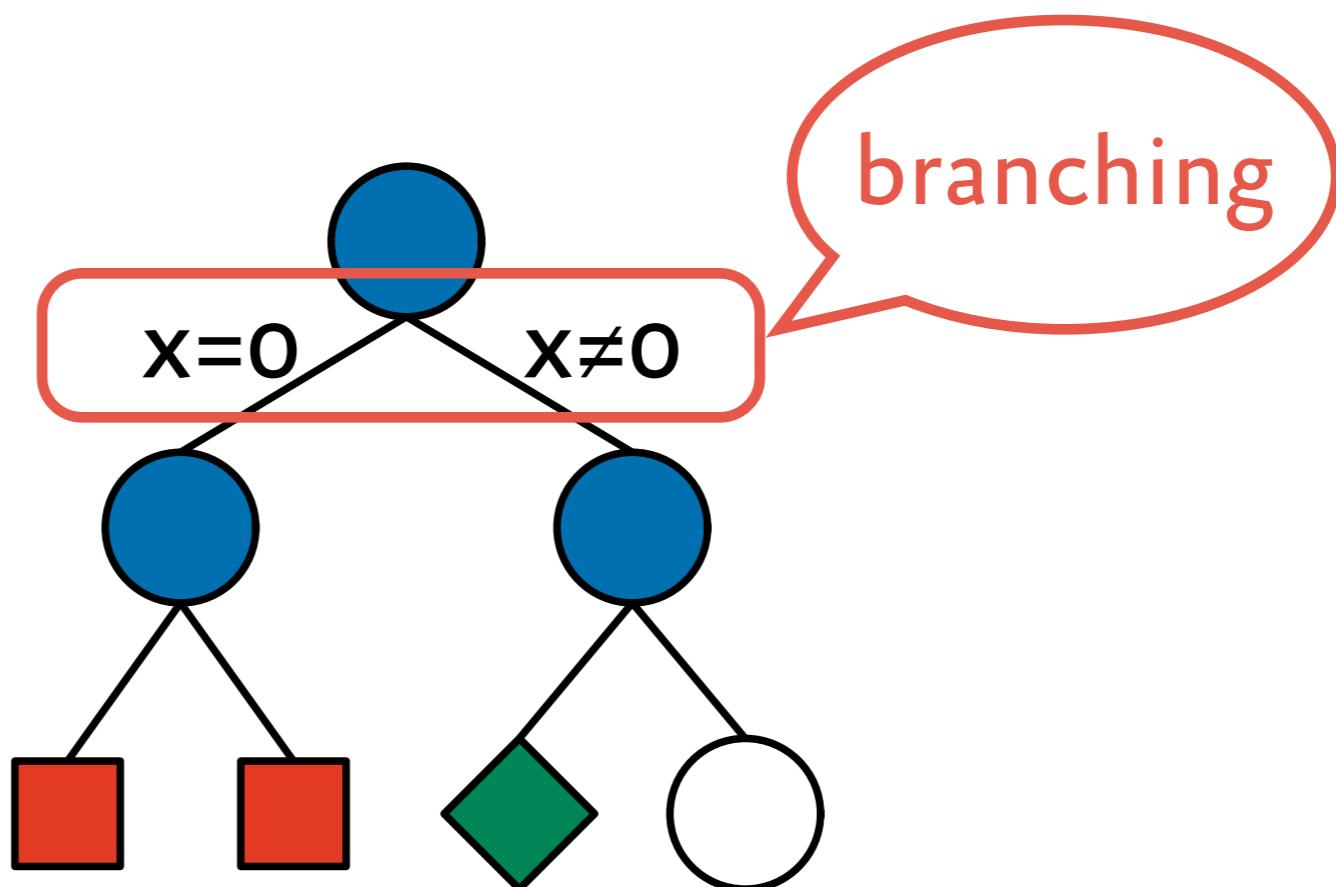
# Search

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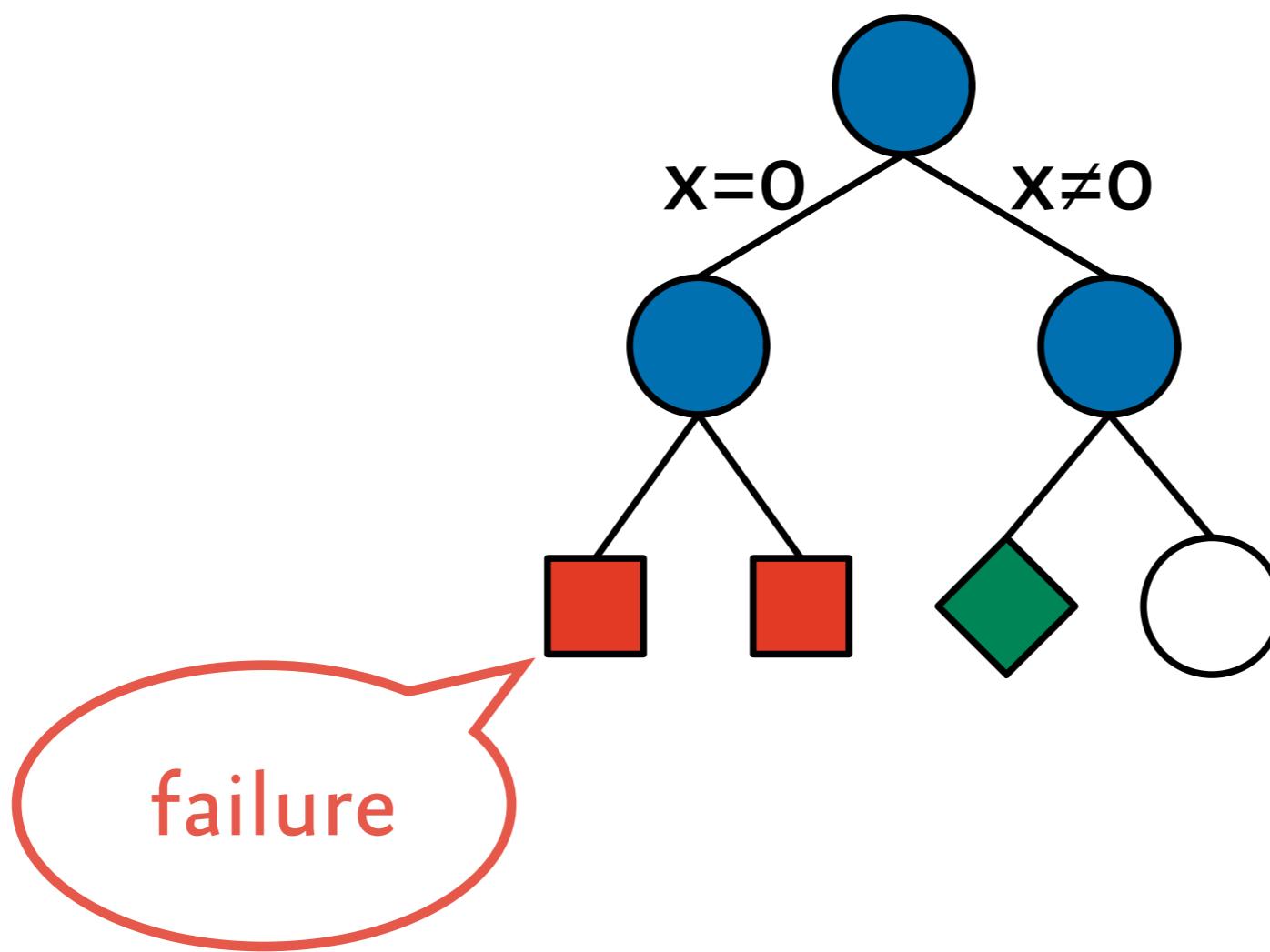
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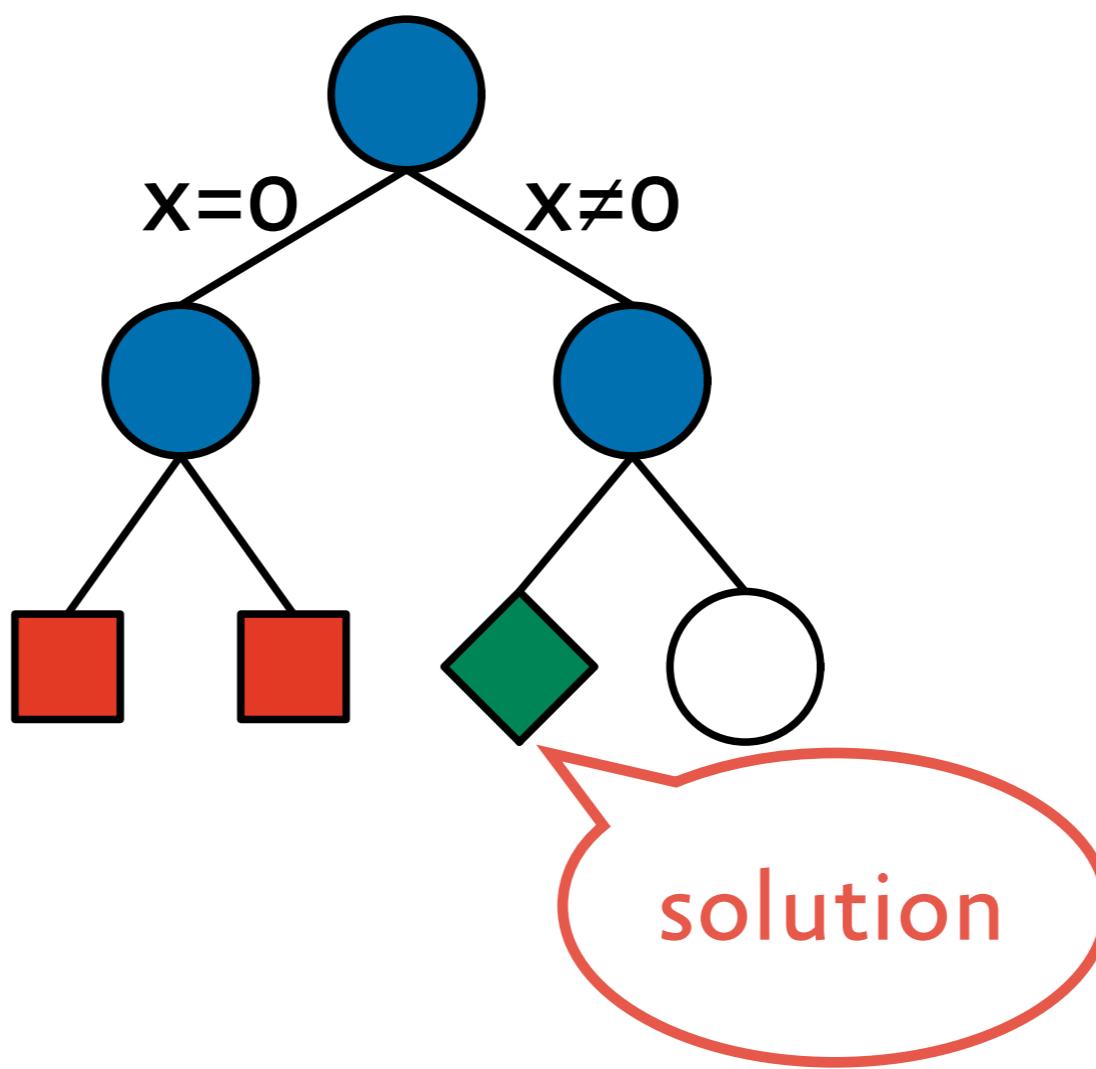
# Search

---



# Search

---



# Send More Money

---

- variables:  $S, E, N, D, M, O, R, Y \in \{0, \dots, 9\}$

- constraints:  $S \neq 0, M \neq 0$

$\text{distinct}(S, E, N, D, M, O, R, Y)$

$$\begin{aligned} & 1000 \times S + 100 \times E + 10 \times N + D \\ & + 1000 \times M + 100 \times O + 10 \times R + E \\ = & 10000 \times M + 1000 \times O + 100 \times N + 10 \times E + Y \end{aligned}$$

# Modelling in Gecode/J

---

- **Implement model as a *script***
  - declare variables
  - post constraints (create propagators)
  - define branching
- **Solve script**
  - basic search strategy (DFS)
  - interactive, graphical search tool (Gist)

# Script: Overview

---

- **Inherit from class Space**
- **Constructor**
  - initialize variables
  - post propagators
  - define branching
- **Copy constructor**
  - copy a space
- **Main function**
  - invoke search engine

# Script: Structure

---

```
import static org.gecode.Gecode.*;
import static org.gecode.GecodeEnumConstants.*;
import org.gecode.*;

public class Money extends Space {
    public VarArray<IntVar> letters;
    public Money() {...}
    public Money(Boolean share, Money money) {...}
    public static void main(String[] args) {...}
}
```

# Script: Structure

import all we need

```
import static org.gecode.Gecode.*;  
import static org.gecode.GecodeEnumConstants.*;  
import org.gecode.*;
```

```
public class Money extends Space {  
    public VarArray<IntVar> letters;  
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}
```

problem variables

# Script: Structure

---

```
import static org.gecode.Gecode.*;  
import static org.gecode.GecodeEnumConstants.*;  
import org.gecode.*;  
  
public class Money extends S  
    public VarArray<IntVar> s;  
    public Money() {...} constructor  
    public Money(Boolean share, Money money) {...}  
    public static void main(String[] args) {...}  
}
```

# Script: Structure

---

```
import static org.gecode.Gecode.*;  
import static org.gecode.GecodeEnumConstants.*;  
import org.gecode.*;  
  
public class Money extends Space {  
    public VarArray<IntVar> lett...  
    public Money() {...}  
    public Money(Boolean share, Money money) {...}  
    public static void main(String[] args) {...}  
}
```

copy constructor

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import org.gecode.*;

public class Money extends Space {
    public VarArray<IntVar> letters;
    public Money() {...}
    public Money(Boolean share, Money money) {...}
    public static void main(String[] args) {...}
}
```

# Script: Constructor

# Script: Constructor

---

```
...
// Refer to the letters by name
IntVar s = letters.get(0);
IntVar e = letters.get(1);
IntVar n = letters.get(2);
IntVar d = letters.get(3);
IntVar m = letters.get(4);
IntVar o = letters.get(5);
IntVar r = letters.get(6);
IntVar y = letters.get(7);
...
```

# Script: Constructor

---

```
...
// Initial letters non-zero
rel(this, s, IRT_NQ, 0);
rel(this, m, IRT_NQ, 0);
// IRT: Integer relation type
...
```

# Posting Constraints

---

- **Defined in the class `org.gecode.Gecode`**
  - accessed with `import static`
- **Check the documentation**
- **All constraints take a space as first argument**
  - where is the constraint to be installed?
  - Scripts are subclasses of Space!

# Linear equation constraints

---

- Propagator for equations of the form

$$\sum_{i=1}^n a_i x_i = d$$

- Specified as arrays

`int[] a`

`VarArray<IntVar> x`

- Supported relations:

`IRT_EQ, IRT_NQ, IRT_LE, IRT_GR, IRT_LQ, IRT_GQ`

# Script: Constructor

---

```
...
// Post linear equation
int a[]={          1000,      100,       10,        1,
                  1000,      100,       10,        1,
-10000, -1000, -100,      -10,       -1};
VarArray<IntVar> x =
    new VarArray<IntVar>(      s, e, n, d,
                                m, o, r, e,
                                m, o, n, e, y);
linear(this, a, x, IRT_EQ, 0);
...
```

# Script: Constructor

---

...

```
// Letters take distinct values  
distinct(this, letters);
```

```
// Find values using first-fail  
branch(this, letters,  
        BVAR_SIZE_MIN,  
        BVAL_MIN);
```

...

# Branching

---

- **Choose variable**

- smallest domain size: BVAR\_SIZE\_MIN
- smallest minimum: BVAR\_MIN\_MIN
- given order: BVAR\_NONE

- **Choose value**

- try smallest value: BVAL\_MIN
- split (lower first) BVAL\_SPLIT\_MIN

# Script: Copying

# Script: Copying

---

```
public Money(Boolean share, Money m) {
    super(share, m);
    letters = new VarArray<IntVar>(this,
                                    share, m.letters);
}
```

copy all variables  
you need for output!

# Script: Copying

# Script: Copying

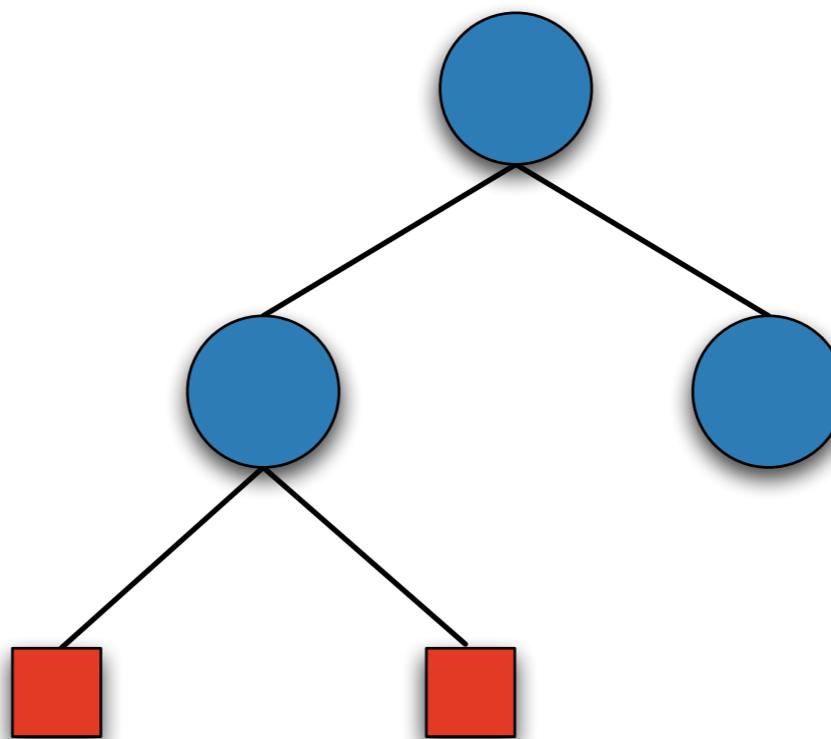
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```
public Money(Boolean share, Money m) {  
    super(share, m);  
    letters = new VarArray<IntVar>(this,  
                                    share, m.letters);  
}
```

copying of single variables also possible!

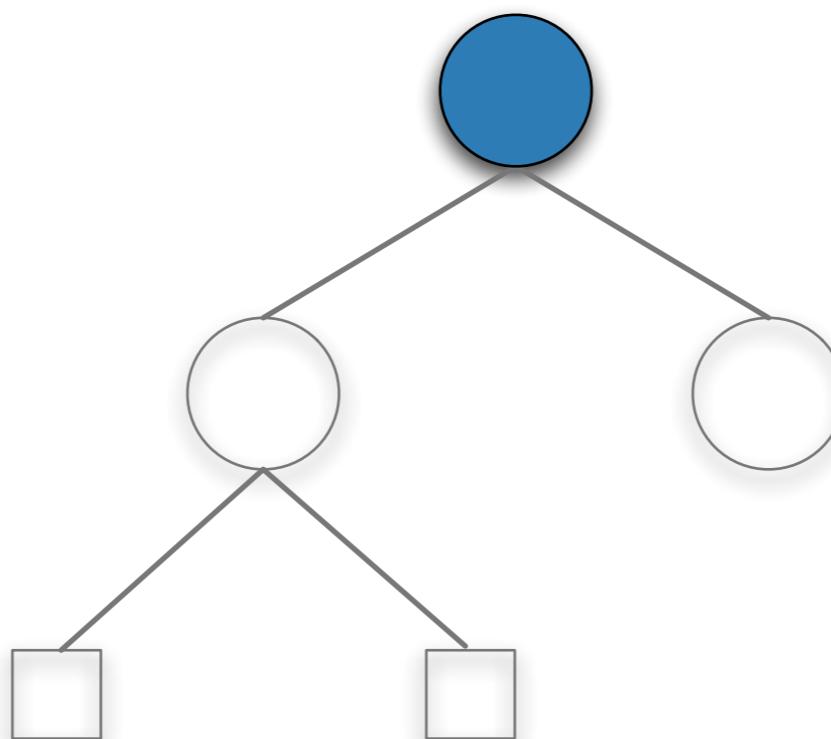
# Why copy? Search!

---



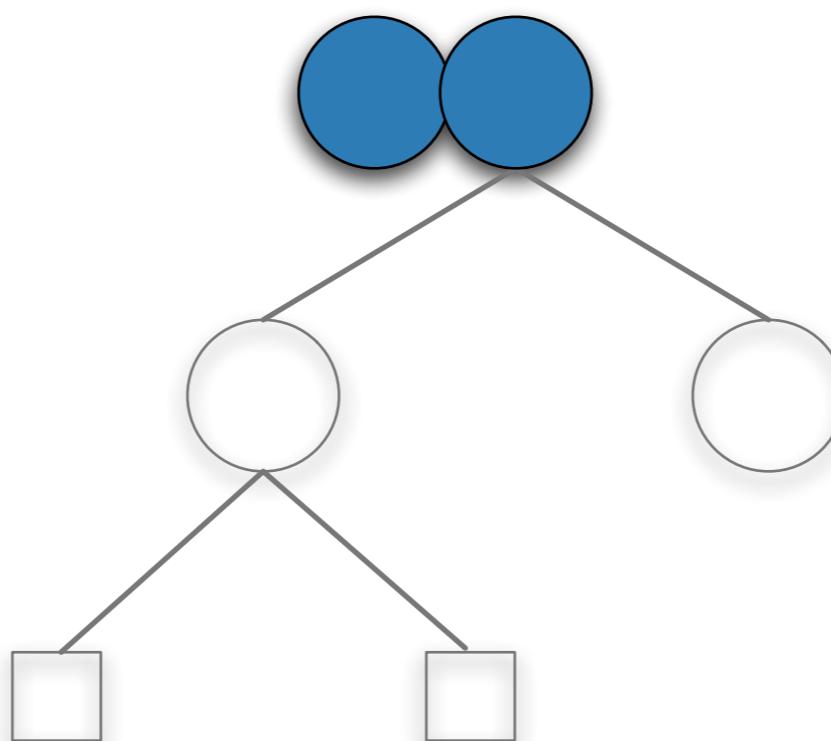
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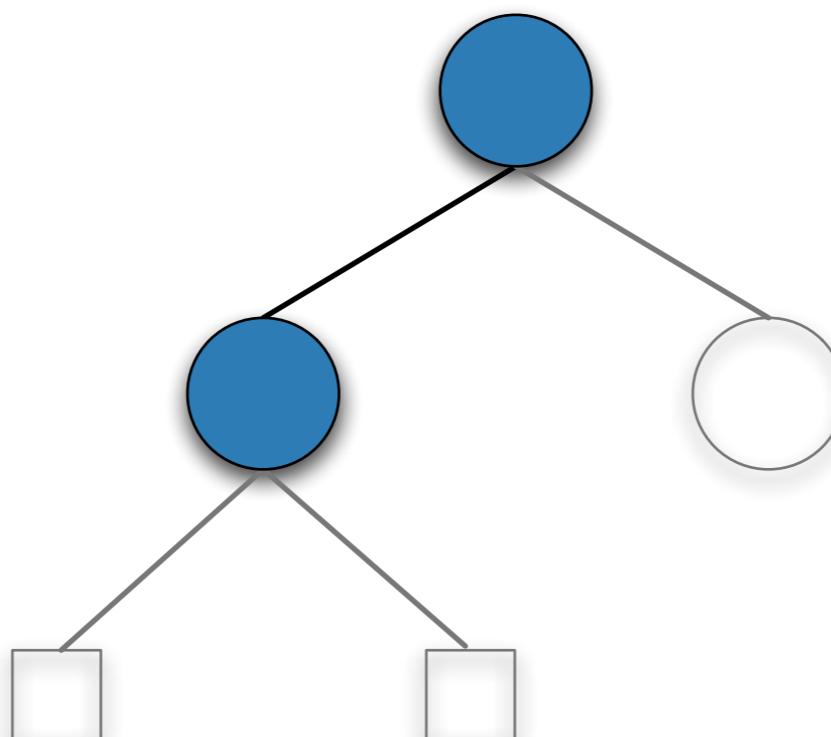
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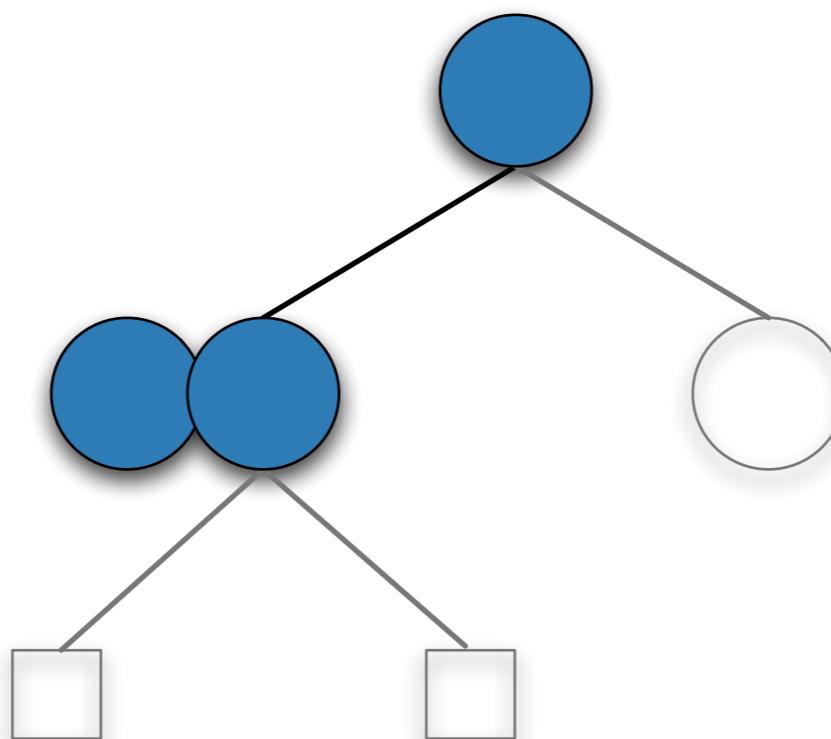
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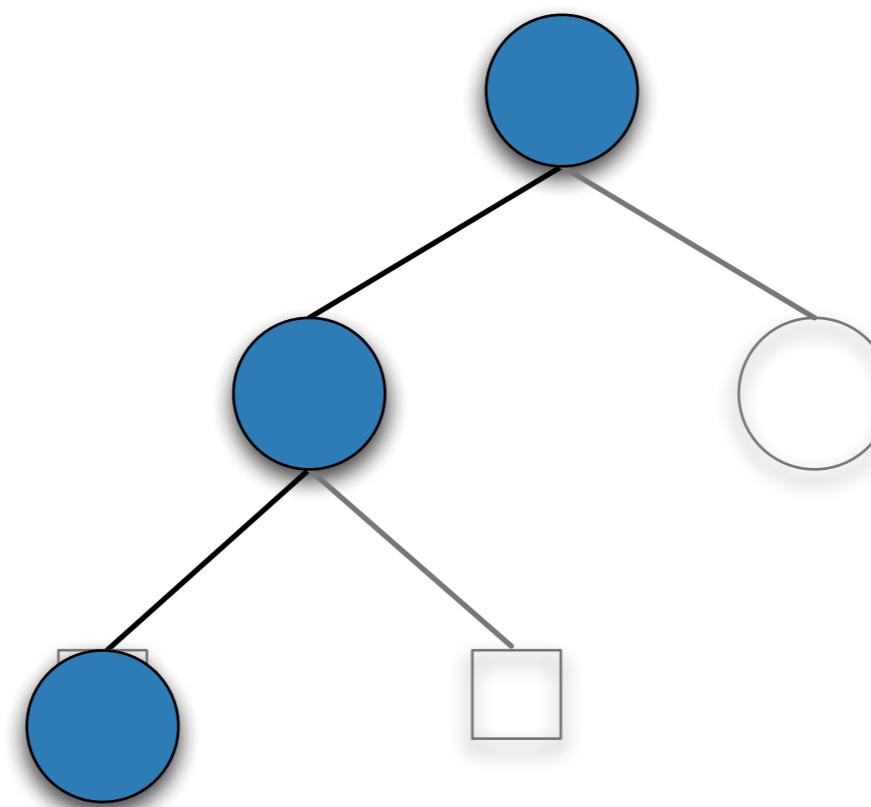
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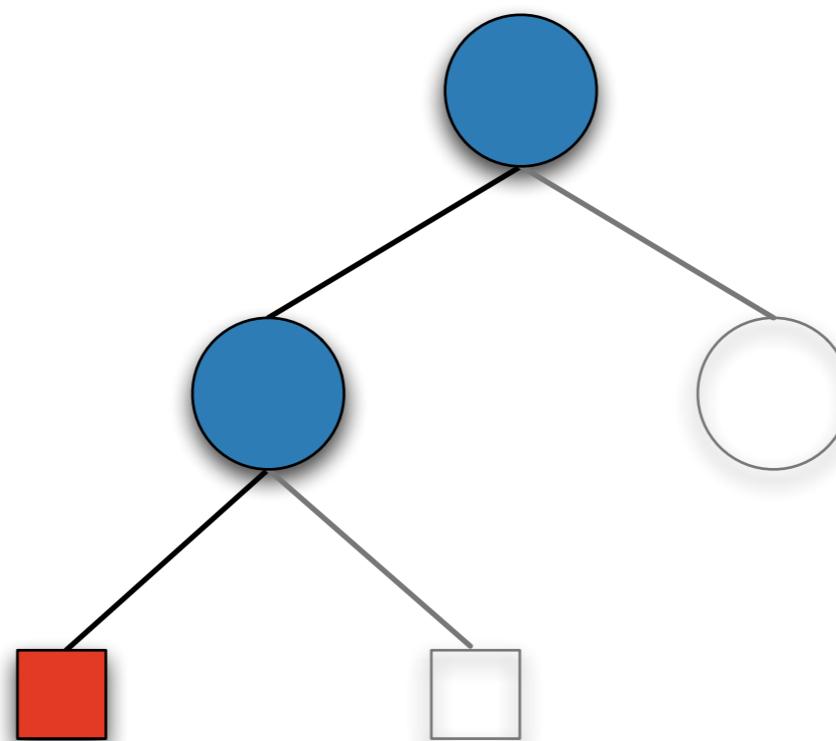
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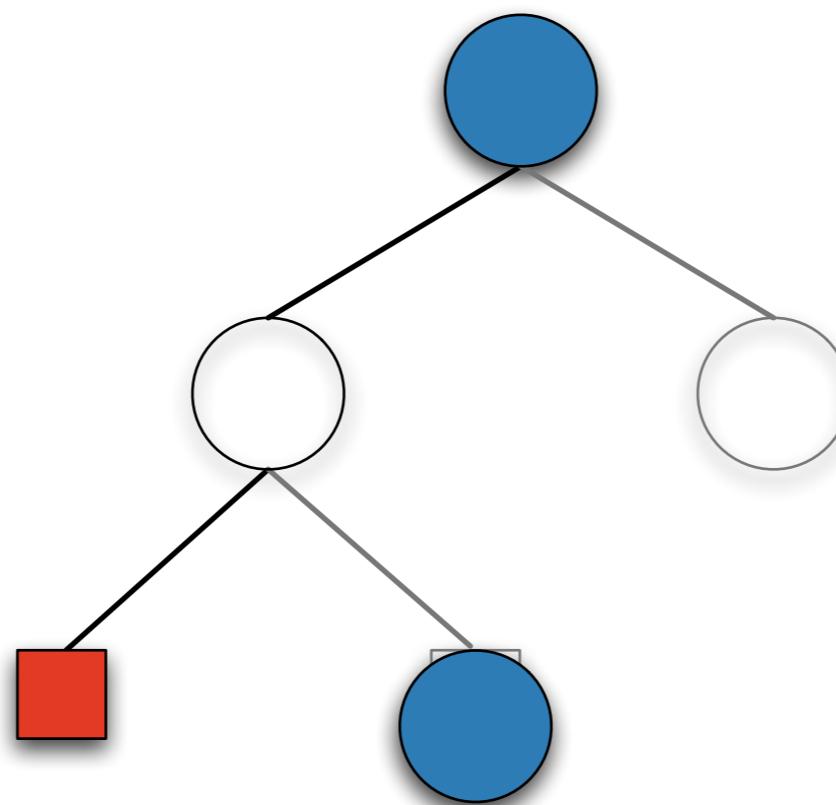
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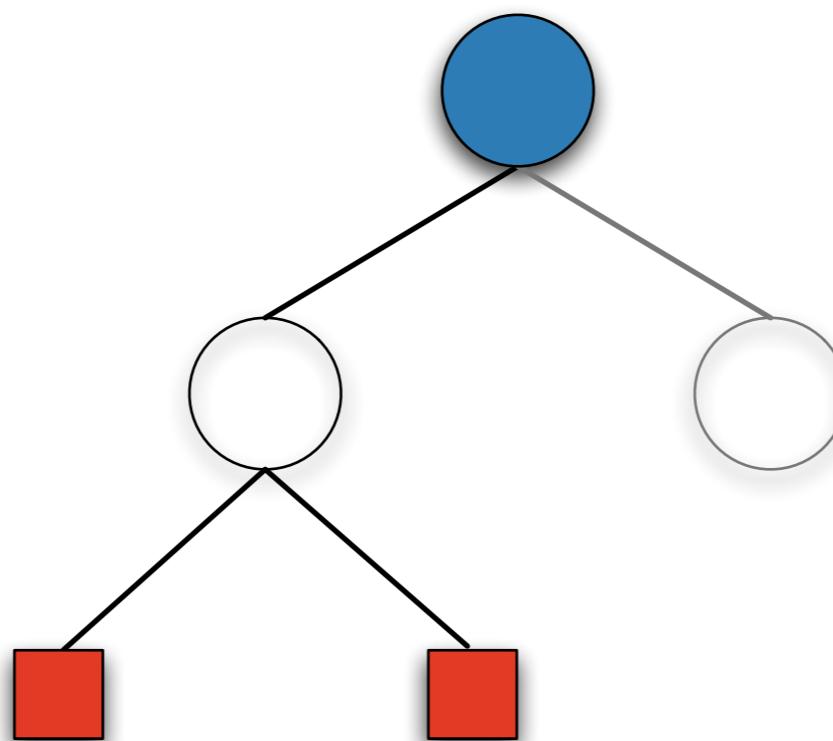
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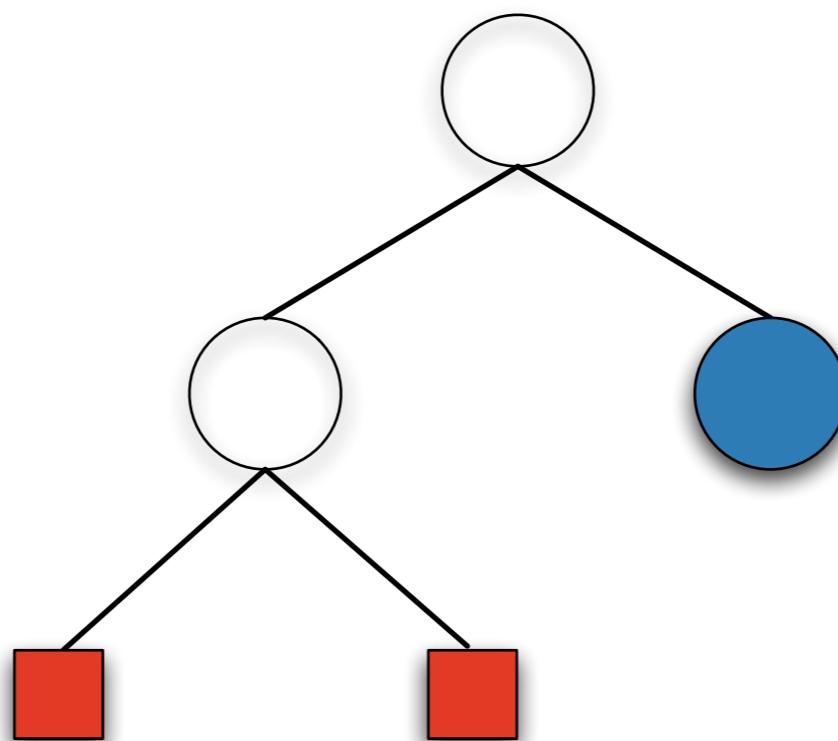
# Why copy? Search!

---



# Why copy? Search!

---



# Script

---

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import static org.gecode.GecodeEnumConstants.*;
import org.gecode.*;

public class Money extends Space {
    public VarArray<IntVar> letters;
    public Money() {...}
    public Money(Boolean share, Money money) {...}
    public static void main(String[] args) {...}
}
```

# Solving

---

- **Hidden in Options class, but...**
- **Search engines:**
  - DFSSearch (depth first search)
  - BABSearch (branch-and-bound search)
- **Interactive search tool**
  - Gist

# First Solution Search

---

```
public static void main(String[] args)
{
    Money m = new Money();
    DFSSearch s = new DFSSearch(m);
    Money sol = (Money) s.next();
    if (sol != null) {
        System.out.println(sol.toString());
    }
}
```

# First Solution Search

---

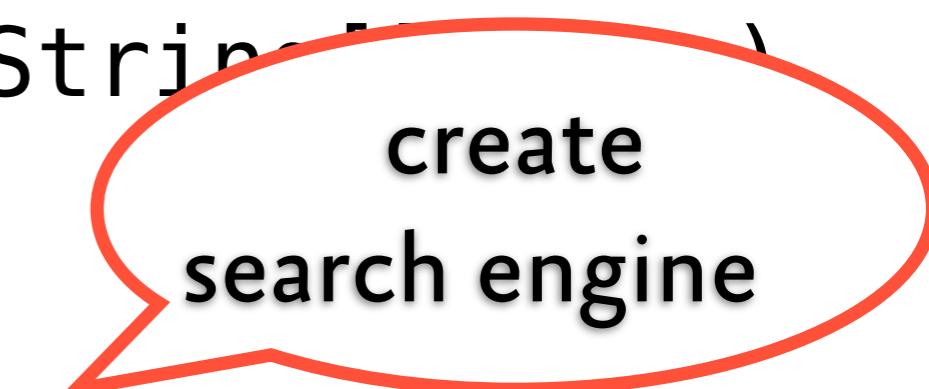
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{  
    Money m = new Money();  
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    Money sol = (Money) s.next();  
    if (sol != null) {  
        System.out.println(sol.toString());  
    }  
}
```

create root  
space

# First Solution Search

---

```
public static void main(String[] args) {  
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    Money sol = (Money) s.next();  
    if (sol != null) {  
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}
```



# First Solution Search

---

```
public static void main(String[] args)
{
    Money m = new Money();
    DFSSearch s = new DFSSearc
    Money sol = (Money) s.next();
    if (sol != null) {
        System.out.println(sol.toString());
    }
}
```



search

# All Solution Search

---

```
public static void main(String[] args)
{
    Money m = new Money();
    DFSSearch s = new DFSSearch(m);
    Money sol = (Money) s.next();
    while (sol != null) {
        System.out.println(sol.toString());
        sol = (Money) s.next();
    }
}
```

# Gecode/J Gist

---

- **Graphical search tree explorer**
  - explore step by step
  - search next solution, search all solutions
  - "inspect" nodes (double-click)
  - hide failed subtrees
  - ...
- **Try it out!**

# Invoking Gist

---

```
import org.gecode.gist.*;  
  
public static void main(String[] args)  
{  
    Money m = new Money();  
    Gist g = new Gist(m);  
    g.exploreOne();  
    // Also possible: g.exploreAll()  
}
```

# Best Solution Search

---

- **Reminder: SMM+**

SEND

+ MOST

= MONEY

- **Constraints:**

Find distinct numbers such that the equation holds and  
MONEY is maximal

# SMM+: Order

---

- **Branch-and-bound principle:**  
after each solution, constrain remaining search to find only better solutions
- **Script provides method:**  
`public void constrain(Space s) { ... }`
- **Invoked on Space object to be constrained**
- **Space s: so far best solution**
  - Only use *values* from s! Never mix variables!

# SMM+: constrain method

---

```
IntVar money;  
public SMM() {  
    ...  
    int [] c = {10000,1000,100,10,1};  
    VarArray<IntVar> l = {m,o,n,e,y}; // pseudocode!  
    linear(this, c, l, IRT_EQ, money);  
    ...  
}  
  
public void constrain(Space bestSol) {  
    SMM smm = (SMM) bestSol;  
    rel(this, money, IRT_GR, smm.money.val());  
}
```

# SMM+: main method

---

```
public static void main(String[] args) {  
    SMM m = new SMM();  
  
    BABSearch s = new BABSearch(m);  
    SMM best = null;  
    SMM sol = (SMM) s.next();  
    while (sol != null) {  
        best = sol; sol = (SMM) s.next();  
    }  
    if (best != null) {  
        System.out.println(best.toString());  
    }  
}
```

# SMM+: Gist

---

```
public static void main(String[] args)
{
    SMM m = new SMM();
    Gist g = new Gist(m, true);
    g.exploreAll();
}
```

# SMM+: Gist

---

```
public static void main(String[] args)
{
    SMM m = new SMM();
    Gist g = new Gist(m, true);
    g.exploreAll();
}
```

switch on b&b

# Solving: Summary

---

- **Non-interactive search:**  
DFSSearch, BABSearch
- **Interactive search:**  
Gist
- **Best solution search:** provide constrain method
- **Search engines independent of script**

# **Some modeling techniques**

---

- **Global constraints**
- **Symmetry breaking**
- **Reification**

# Global constraints

---

- **Classic example:**

$$x, y, z \in \{1, 2\}, \quad x \neq y, x \neq z, y \neq z$$

- **No solution!**
- **But: each individual constraint still satisfiable!**  
⇒ no propagation possible!
- **Solution:** look at several constraints at once

**distinct(x,y,z)**

# Distinct

---

- Remember last exercise for Sudoku?

"Experiment with different ... propagator strengths."

- ICL\_VAL: same as  $x \neq y, x \neq z, y \neq z$
- ICL\_BND: stronger
- ICL\_DOM: strongest possible propagation

# Grocery Puzzle

---

- A kid buys four items in a grocery store.
- Cashier: "That's €7,11."

Hold on! I multiplied instead of adding.

Wow, the sum is also €7,11!"

- What are the individual prices of the four items?

# Grocery Puzzle

---

- **Variables:**

$A, B, C, D \in \{1, \dots, 711\}$  (price in cents)

- **Constraints:**

- $A + B + C + D = 711$
- $A * B * C * D = 711 * 100 * 100 * 100$

# Grocery Puzzle

---

- **Branching:**
  - Bad idea: try values one by one
  - Better: split domains
- **Typically good strategy for problems with arithmetic constraints**
- **Still:**

# Grocery Puzzle: Symmetries

---

- Many solutions are equivalent!
  - swap values of A,B,C,D
  - Let's order them:
    - $A \leq B \leq C \leq D$
  - This is called

*Symmetry Breaking*

- So let's see...

# Grocery Puzzle: Symmetries

---

- **Symmetry breaking also works on symmetric failure!**
- **Example:**
  - Suppose A,B,C have been assigned 1,2,3 by search.
  - We find no value for D such that we get a solution.
  - No need to try A=2, B=1, C=3!
- **Ruled out by  $A \leq B \leq C \leq D$**

# Grocery Puzzle: More Symmetries

---

- **Observation:** 711 has prime factor 79

$$711 = 79 \times 9$$

- **So assume**

$$A = 79 \times X \quad (\text{for a "fresh" variable } X)$$

- **Remove  $A \leq B$**
- **And now...**

# Reified constraints

---

- **Constraints are in a big conjunction**
- **How about disjunctive constraints?**

$$A+B=C \vee C=0$$

- **Solution: *reify* the constraints:**

$$(A+B=C \Leftrightarrow b0) \wedge$$

$$(C=0 \Leftrightarrow b1) \wedge$$

$$(b0 \vee b1 \Leftrightarrow \text{true})$$

# Reified constraints

---

```
int[] ones = [1,1,-1];
VarArray<IntVar> xs = {a,b,c};
BoolVar b0(this);
BoolVar b1(this);

linear(this, ones, xs, IRT_EQ, 0, b0);
rel(this, c, IRT_EQ, 0, b1);
bool_or(this, b0, b1, true);
```

# What we've learned today

---

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- We need **copying** for backtracking during search
- **Global constraints** can provide stronger inferences
- **Symmetry breaking** is essential for some problems

# What we've learned today

---

- Use **scripts** to model constraint problems
- **Posting a propagator** installs it inside a space
- We need **copying** for backtracking during search
- **Global constraints** can provide stronger inferences
- **Symmetry breaking** is essential for some problems
- **Reification** allows for arbitrary Boolean combinations of constraints

# Graded lab: temporal relations

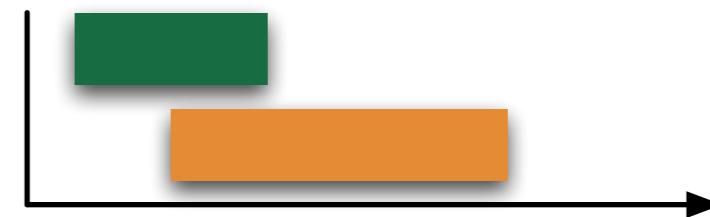
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- Given:
  - a number of events
  - constraints between events:
    - *a* ends before *b*
    - *a* and *b* do not overlap
    - *a* happens during *b*
    - ...

# Graded lab: temporal relations

---

- Given:
  - a number of events
  - constraints between events:
    - *a* ends before *b*
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    - *a* happens during *b*
    - ...



# Graded lab: temporal relations

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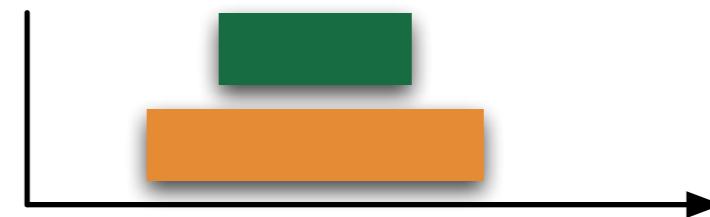
- Given:
  - a number of events
  - constraints between events:
    - *a* ends before *b*
    - *a* and *b* do not overlap
    - *a* happens during *b*
    - ...



# Graded lab: temporal relations

---

- Given:
  - a number of events
  - constraints between events:
    - *a* ends before *b*
    - *a* and *b* do not overlap
    - *a* happens during *b*
    - ...



# Graded lab: temporal relations

---

- Data structure:

```
enum Relation { PRECEDES, MEETS, OVERLAPS, DURING,  
    STARTS, FINISHES, EQUALS};  
  
class Item {  
    String act1; Relation rel; String act2;  
}  
Vector<Vector<Item>> problem;
```

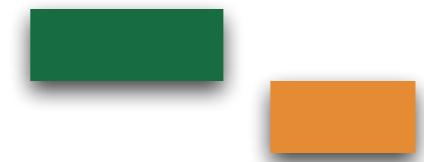


CNF

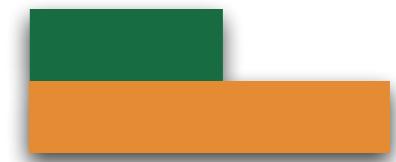
# Graded lab: temporal relations

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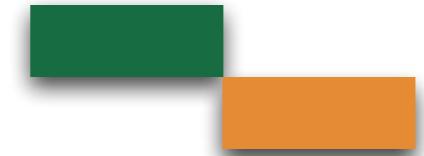
A precedes B



A starts B



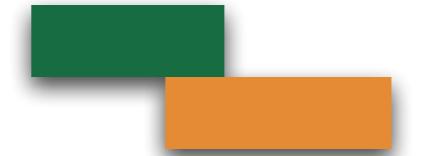
A meets B



A finishes B



A overlaps B



A equals B



A during B



# Graded lab: temporal relations

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- **Your task:**
  - create script that solves temporal relation problems
- **If you have too much time:**
  - create visualization for the solutions
- **Submit**
  - by Monday, April 30, 24:00 MESZ
  - by email to [tack@ps.uni-sb.de](mailto:tack@ps.uni-sb.de)

**Thanks for your attention!**  
**See you on Thursday.**